

KR 16 R2010



Technical data

Maximum reach	2013 mm
Rated payload	16 kg
Maximum payload	19.2 kg
Maximum supplementary load, rotating column / link arm / arm	-
Pose repeatability (ISO 9283)	± 0.04 mm
Number of axes	6
Mounting position	Floor; Ceiling; Wall; Desired angle
Footprint	430.5 mm x 370 mm
Weight	approx. 255 kg

Axis data

Motion range	
A1	±185 °
A2	-185 ° / 65 °
A3	-138 ° / 175 °
A4	±350 °
A5	±130 °
A6	±350 °
Speed with rated payload	
A1	200 °/s
A2	175 °/s
A3	190 °/s
A4	430 °/s
A5	430 °/s
A6	630 °/s

Operating conditions

Ambient temperature during operation	5 °C to 45 °C (278 K to 318 K)
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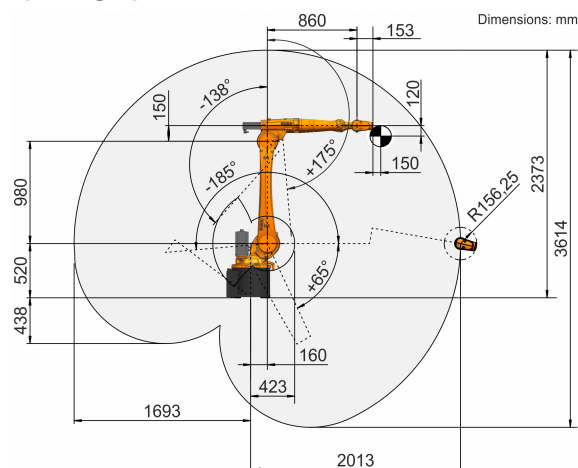
Protection rating

Protection rating (IEC 60529)	IP65
Protection rating, robot wrist (IEC 60529)	IP65

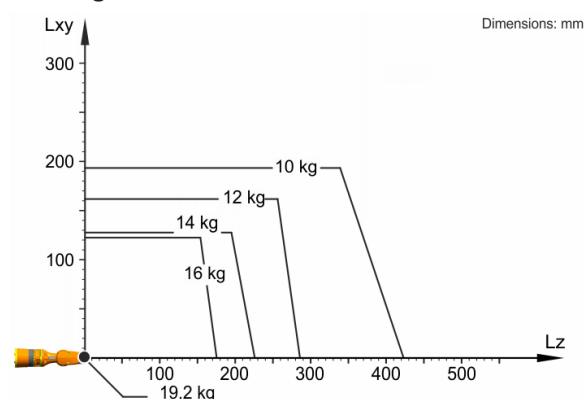
Controller

Controller	KR C4
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Workspace graphic



Payload diagram



The KR 16 R2010 is designed for a rated payload of 16 kg in order to optimize the dynamic performance of the robot. With reduced load center distances and favorable supplementary loads, a maximum payload of up to 19.2 kg can be mounted. The specific KUKA Load case must be verified using KUKA. For further consultation, please contact KUKA Service.

Mounting flange

