

# LR Mate 200iD

**FANUC**

Max. load capacity  
at wrist: 7 kg

Max. reach:  
717 mm

Series	Robot			Reach (mm)	Controlled axes	Repeatability (mm)	Mechanical weight (kg)	Motion range (°)						Maximum speed (°/s)						Moments (N·m)/Inertia (kg·m <sup>2</sup> )			Protection		
	Version	Type	Max.load capacity at wrist (kg)					J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6	J4 Moment/ Inertia	J5 Moment/ Inertia	J6 Moment/ Inertia	Average Power consumption (kW)	Body standard/ optional	Wrist & J3 arm standard/ optional
LR Mate 200	iD	-	7	717	6	± 0.01**	25	340 (360)	245	420	380	250	720	450	380	520	550	545	1000	16.6/.47	16.6/.47	9.4/.15	0.5	IP67/ IP69K	IP67/ IP69K

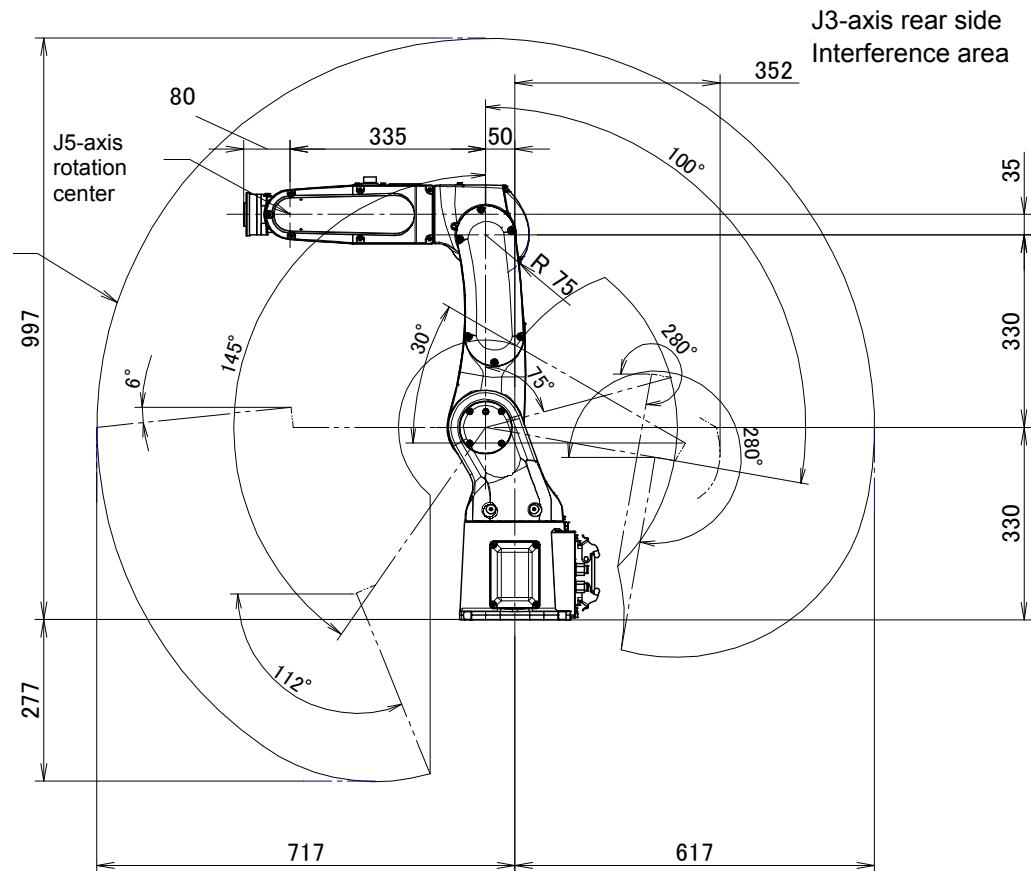
(option) ● standard ○ on request - not available [ ] with hardware and/or software option \*\* Based on ISO9283

LR Mate 200iD



Standard model (2 integrated solenoid valves)

Operating space  
of J5-axis rotation  
center



LR Mate 200iD

>> If applied load on the robot exceeds 5kg when the robot is installed on an angle, the operating area is limited by the mount angle. If payload is less than 5kg, there is no restriction of the operating space.